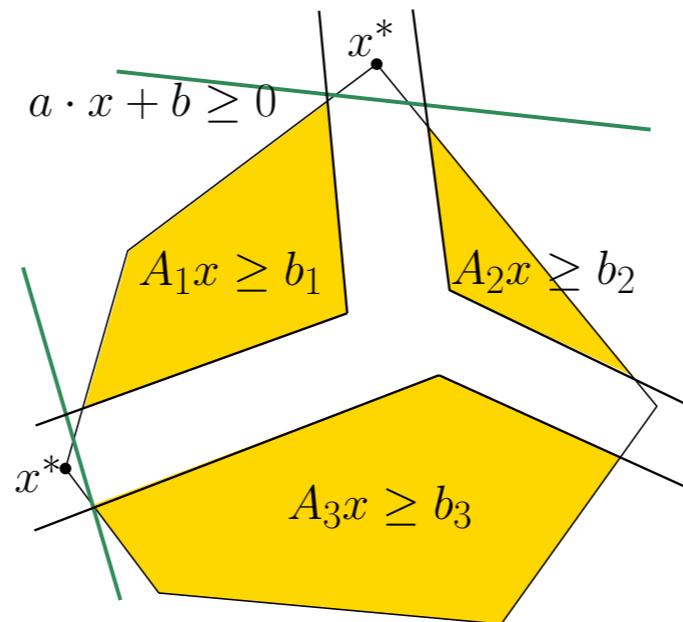


# Cut Generating SDPs : A disjunctive framework for MINLPs with polynomial constraints

Amitabh Basu and Sam Burer

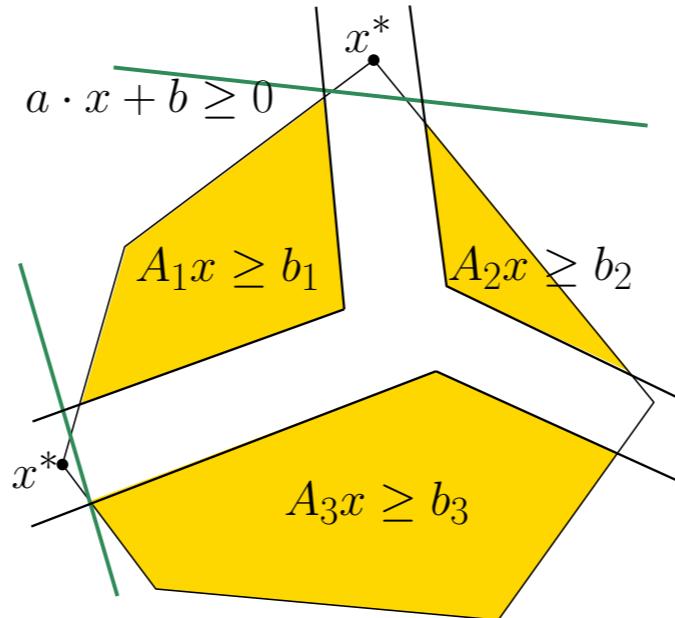
MINLP workshop, CMU Pittsburgh, June 2, 2014

# Balas' CGLPs : A disjunctive framework for the polyhedral world



# Balas' CGLPs : A disjunctive framework for the polyhedral world

Farkas'  
Lemma



$$\min x^* \cdot a + b$$

$$\text{s.t. } a^T = \lambda_i^T A_i \quad i = 1, 2, 3$$

$$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$$

$$\lambda_i \geq 0 \quad i = 1, 2, 3$$

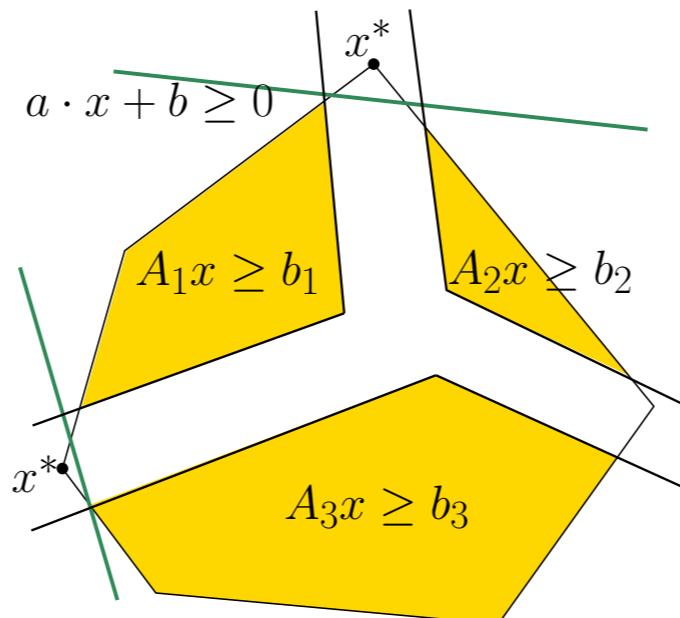
+ Normalizing constraints

Variables :  $a, b, \lambda_i$

CGLP

# Balas' CGLPs : A disjunctive framework for the polyhedral world

Farkas'  
Lemma



$$\min x^* \cdot a + b$$

$$\text{s.t. } a^T = \lambda_i^T A_i \quad i = 1, 2, 3$$

$$A_i x_i - b_i t_i = 0 \quad i = 1, 2, 3$$

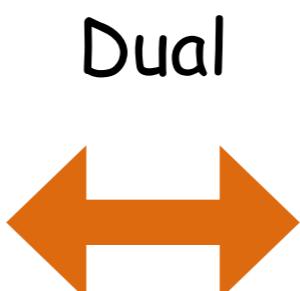
CGLP

$$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$$

$$\lambda_i \geq 0 \quad i = 1, 2, 3$$

+ Normalizing constraints

Variables :  $a, b, \lambda_i$



$$x_1 + x_2 + x_3 = x$$

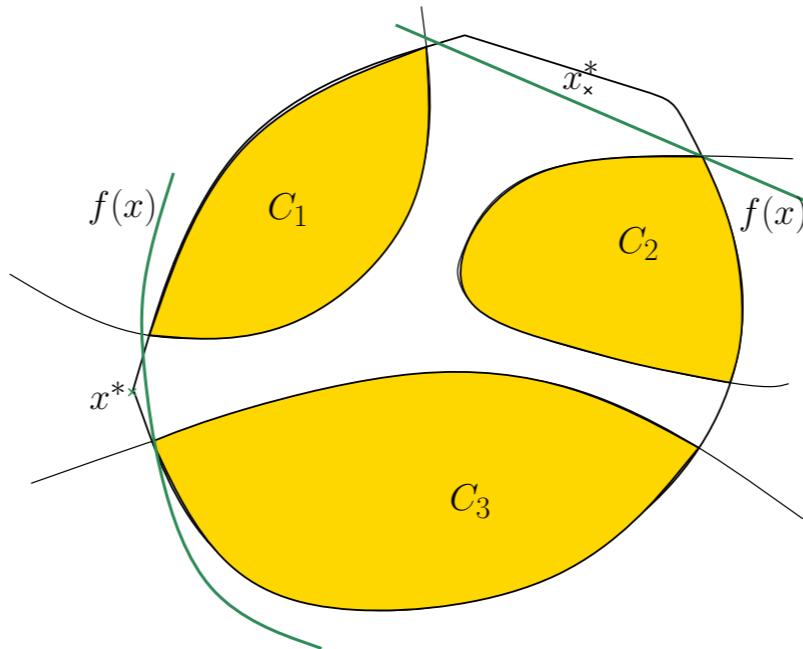
$$t_1 + t_2 + t_3 = 1$$

Extended  
Formulation

$$t_i \geq 0 \quad i = 1, 2, 3$$

# Cut Generating SDPs (CGSDPs) : A disjunctive framework for the polynomial constraints

Farkas' Lemma



$$\min x^* \cdot a + b$$

$$\text{s.t. } a^T = \lambda_i^T A_i \quad i = 1, 2, 3$$

$$A_i x_i - b_i t_i = 0 \quad i = 1, 2, 3$$

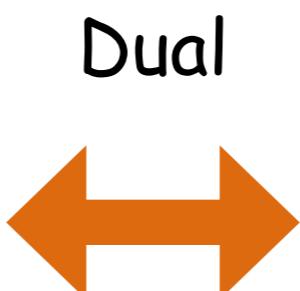
$$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$$

$$x_1 + x_2 + x_3 = x$$

$$\lambda_i \geq 0 \quad i = 1, 2, 3$$

$$t_1 + t_2 + t_3 = 1$$

+ Normalizing constraints



Variables :  $a, b, \lambda_i$

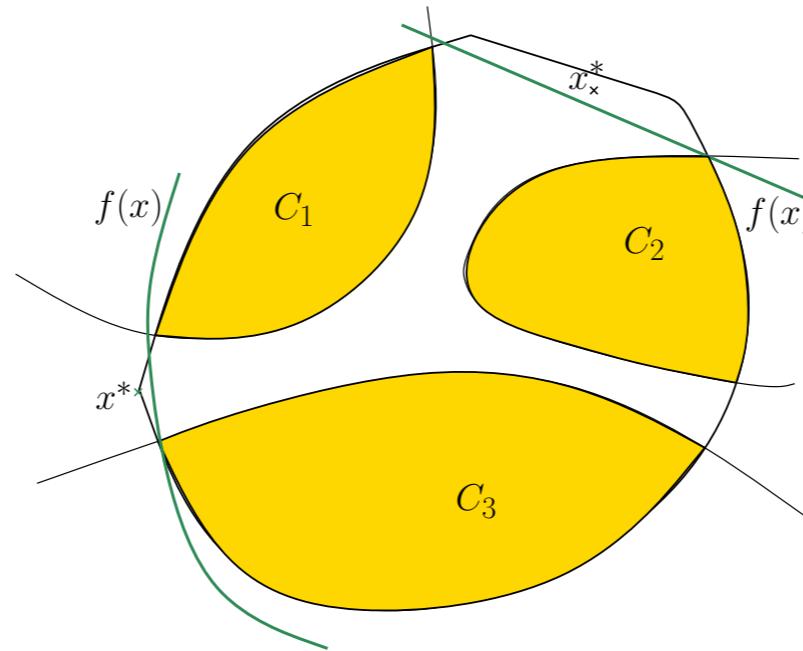
$$t_i \geq 0 \quad i = 1, 2, 3$$

CGLP

Extended Formulation

# Cut Generating SDPs (CGSDPs) : A disjunctive framework for the polynomial constraints

Positivstellensatz:  
Nonlinear  
Farkas' Lemma



$$\min x^* \cdot a + b$$

$$\text{s.t. } a^T = \lambda_i^T A_i \quad i = 1, 2, 3$$

$$A_i x_i - b_i t_i = 0 \quad i = 1, 2, 3$$

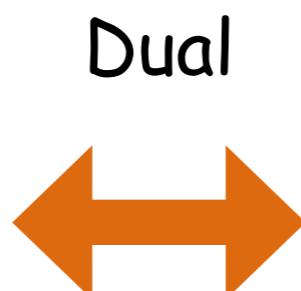
CGLP

$$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$$

$$\lambda_i \geq 0 \quad i = 1, 2, 3$$

+ Normalizing constraints

Variables :  $a, b, \lambda_i$



$$x_1 + x_2 + x_3 = x$$

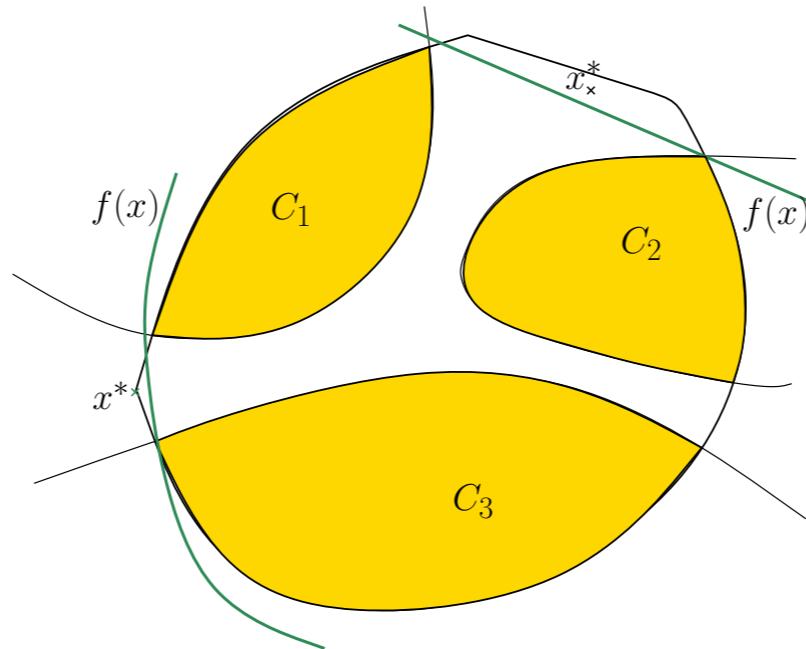
$$t_1 + t_2 + t_3 = 1$$

Extended  
Formulation

$$t_i \geq 0 \quad i = 1, 2, 3$$

# Cut Generating SDPs (CGSDPs) : A disjunctive framework for the polynomial constraints

Positivstellensatz:  
Nonlinear  
Farkas' Lemma



$$\min x^* \cdot a + b$$

s.t.  $a^T = \lambda_i^T A_i \quad i = 1, 2, 3$

$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$

$\lambda_i \geq 0 \quad i = 1, 2, 3$

+ Normalizing constraints

Variables :  $a, b, \lambda_i$

CGSDP

Dual



$$A_i x_i - b_i t_i = 0 \quad i = 1, 2, 3$$

$$x_1 + x_2 + x_3 = x$$

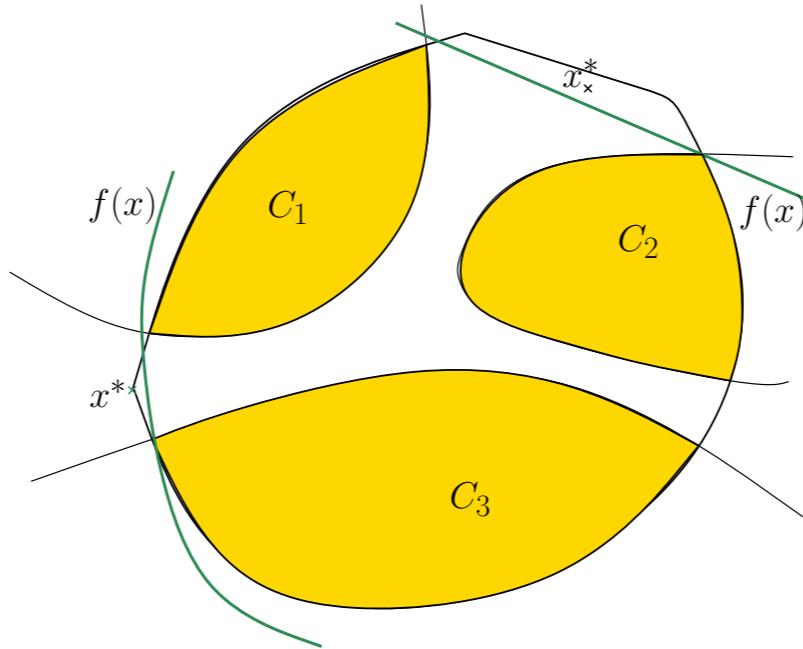
$$t_1 + t_2 + t_3 = 1$$

Extended  
Formulation

$$t_i \geq 0 \quad i = 1, 2, 3$$

# Cut Generating SDPs (CGSDPs) : A disjunctive framework for the polynomial constraints

Positivstellensatz:  
Nonlinear  
Farkas' Lemma



$$\min x^* \cdot a + b$$

$$\text{s.t. } a^T = \lambda_i^T A_i \quad i = 1, 2, 3$$

$$A_i x_i - b_i t_i = 0 \quad i = 1, 2, 3$$

$$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$$

Dual

$$\lambda_i \geq 0 \quad i = 1, 2, 3$$

$$x_1 + x_2 + x_3 = x$$

+ Normalizing constraints

$$t_1 + t_2 + t_3 = 1$$

Variables :  $a, b, \lambda_i$

$$t_i \geq 0 \quad i = 1, 2, 3$$

CGSDP

Extended  
Formulation



# Cut Generating SDPs (CGSDPs) : A disjunctive framework for the polynomial constraints

Positivstellensatz:  
Nonlinear  
Farkas' Lemma

$$\min x^* \cdot a + b$$

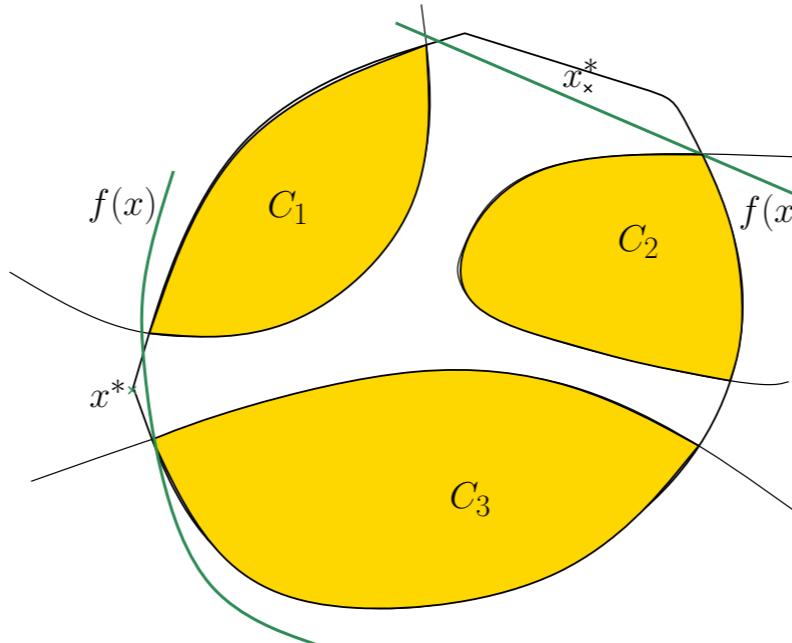
$$\text{s.t. } a^T = \lambda_i^T A_i \quad i = 1, 2, 3$$

$$\lambda_i^T b_i + b \geq 0 \quad i = 1, 2, 3$$

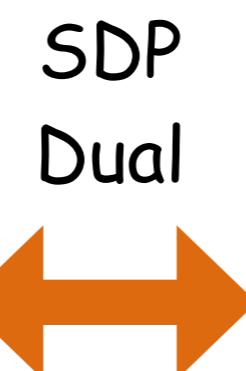
$$\lambda_i \geq 0 \quad i = 1, 2, 3$$

+ Normalizing constraints

Variables :  $a, b, \lambda_i$



CGSDP



$$A_i x_i - b_i t_i = 0 \quad i = 1, 2, 3$$

$$x_1 + x_2 + x_3 = x$$

$$t_1 + t_2 + t_3 = 1$$

Extended  
Formulation as  
SDP

$$t_i \geq 0 \quad i = 1, 2, 3$$

*See you at  
my poster !!*