

A feasibility pump for nonconvex MINLP

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$$\begin{aligned} \min \quad & f(\mathbf{x}) \\ \text{s.t.} \quad & \mathbf{g}(\mathbf{x}) \leq \mathbf{0} \\ & \mathbf{x} \in \mathbb{Z}^p \times \mathbb{R}^{n-p} \cap [\ell, \mathbf{u}] \end{aligned}$$

Assume f and $\mathbf{g} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ are **factorable**, i.e. are composed by combining variables and constants with operators from a finite set $\mathcal{O} = \{+, -, \times, \wedge, /, \log, \sin, \cos\}$

Feasibility pump heuristics¹

Feasibility Pump heuristics are suited for problems where

- ▶ integrality constraints: $\mathbf{x} \in \mathcal{I} = \mathbb{Z}^p \times \mathbb{R}^{n-p}$ and
- ▶ continuous constraints: $\mathbf{x} \in \mathcal{C} = \{\mathbf{x} \in \mathbb{R}^n : \mathbf{g}(\mathbf{x}) \leq \mathbf{0}\}$

coexist, such as MILP and MINLP.

Idea: generate two sequences of (possibly infeasible) solutions:

- ▶ $(\hat{\mathbf{x}}^k)_{k \in \mathbb{N}}$: satisfies integrality, i.e., $\hat{\mathbf{x}}^k \in \mathcal{I}$
- ▶ $(\tilde{\mathbf{x}}^k)_{k \in \mathbb{N}}$: satisfies continuous constraints, i.e., $\tilde{\mathbf{x}}^k \in \mathcal{C}$

The next point of sequence $(\tilde{\mathbf{x}}^k)$ is the closest to the previous point of sequence $(\hat{\mathbf{x}}^k)$ and viceversa.

¹M. Fischetti, F. Glover, A. Lodi, “The feasibility pump”, *Math. Prog.* 104(1):91-104, 2005.

Feasibility pump heuristics

Initialization: $\tilde{\mathbf{x}}^0 \in \mathcal{C}$.

1. $k \leftarrow 1$
2. repeat
3. $\hat{\mathbf{x}}^k \in \operatorname{argmin}_{\mathbf{x} \in \mathcal{I}} \|\mathbf{x} - \tilde{\mathbf{x}}^{k-1}\|$
4. $\tilde{\mathbf{x}}^k \in \operatorname{argmin}_{\mathbf{x} \in \mathcal{C}} \|\mathbf{x} - \hat{\mathbf{x}}^k\|$
5. $k \leftarrow k + 1$
6. until $\hat{\mathbf{x}}^k$ or $\tilde{\mathbf{x}}^k$ is feasible

The MILP feasibility pump

Consider

$$(\text{MILP}) \quad \min\{\mathbf{c}^\top \mathbf{x} : \mathbf{Ax} \leq \mathbf{b}, \mathbf{x} \in \mathbb{Z}^p \times \mathbb{R}^{n-p}\}$$

Set $\tilde{\mathbf{x}}^0 \in \operatorname{argmin}\{\mathbf{c}^\top \mathbf{x} : \mathbf{Ax} \leq \mathbf{b}\}$ and $k = 1$. Then

$$\hat{\mathbf{x}}^k = \lfloor \tilde{\mathbf{x}}^k \rfloor$$

$$\tilde{\mathbf{x}}^k \in \operatorname{argmin}\{\|\mathbf{x} - \hat{\mathbf{x}}^{k-1}\|_1 : \mathbf{Ax} \leq \mathbf{b}\}$$

Variants

The original FP finds a feasible, but often bad, initial solution.

- ▶ The objective function $\mathbf{c}^\top \mathbf{x}$ is ignored

⇒ Objective FP²:

$$\begin{aligned}\hat{\mathbf{x}}^k &= \lfloor \tilde{\mathbf{x}}^k \rfloor \\ \tilde{\mathbf{x}}^k &\in \operatorname{argmin}\{\alpha \|\mathbf{x} - \hat{\mathbf{x}}^{k-1}\|_1 + \beta \mathbf{c}^\top \mathbf{x} : \mathbf{Ax} \leq \mathbf{b}\}\end{aligned}$$

Feasibility Pump 2.0³:

- ▶ better rounding heuristics than $\lfloor \mathbf{x} \rfloor$
- ▶ perturbation in the event of cycling

²T. Achterberg, T. Berthold, “Improving the feasibility pump”. *Discrete Optimization* 4(1):77-86, 2007.

³M. Fischetti, D. Salvagnin, “Feasibility pump 2.0”, *Math. Prog. Comp.* 1(2-3):201-222, 2009.

FP for convex MINLP⁴

The first attempt to port the FP to the MINLP realm.

- ▶ The two sequences obtained by solving two simpler problems:
 - ▶ an NLP problem
 - ▶ a MILP approximation of the MINLP
- ▶ MILP provided by Outer Approximation:

$$\begin{aligned} \min \quad & z \\ \text{s.t.} \quad & f(\tilde{\mathbf{x}}^k) + \nabla f(\tilde{\mathbf{x}}^k)(\mathbf{x} - \tilde{\mathbf{x}}^k) \leq z \\ & g_i(\tilde{\mathbf{x}}^k) + \nabla g_i(\tilde{\mathbf{x}}^k)(\mathbf{x} - \tilde{\mathbf{x}}^k) \leq 0 \quad \forall i = 1, 2, \dots, m \end{aligned}$$

⁴P. Bonami, G. Cornuéjols, A. Lodi, F. Margot, "A Feasibility Pump for Mixed Integer Nonlinear Programs." *Math. Prog.* 119(2):331-352, 2009.

Nonconvex MINLP

- ▶ integrality constraints: $\mathbf{x} \in \mathcal{I} = \mathbb{Z}^p \times \mathbb{R}^{n-p}$ and
- ☹ nonconvex continuous constraints:

$$\mathbf{x} \in \mathcal{C} = \{\mathbf{x} \in \mathbb{R}^n : \mathbf{g}(\mathbf{x}) \leq \mathbf{0}\}$$

Previous attempts try to solve (even heuristically) the continuous nonconvex problem through a global solver or multi-start⁵

⁵C. D'Ambrosio, A. Frangioni, L. Liberti, A. Lodi, "Experiments with a feasibility pump approach for nonconvex MINLPs", Proceedings of SEA 2010.

Nonconvex MINLP: idea

Take advantage of features of both the solver and the problem.

- ▶ convexification cuts: use a valid LP relaxation rather than Outer Approximation
- ▶ nonlinearity: use second-order information
- ▶ MILP: diversify search

FP: component problems

Global optimization techniques construct an (MI)LP relaxation by adding q auxiliary variables.

$$\begin{aligned} \text{(MILP)} \quad & \min \quad x_{n+q} \\ & \text{s.t.} \quad \mathbf{Ax} \geq \mathbf{b} \\ & \quad \mathbf{x} \in (\mathbb{Z}^s \times \mathbb{R}^{n+q-s}) \cap [\ell', \mathbf{u}'] \end{aligned}$$

so redefine our components:

$$\begin{aligned} \mathcal{C} &= \{\mathbf{x} \in \mathbb{R}^n \cap [\ell, \mathbf{u}] : \mathbf{g}(\mathbf{x}) \leq \mathbf{0}\} \\ \mathcal{I} &= \{\mathbf{x} \in \mathbb{Z}^s \times \mathbb{R}^{n+q-s} \cap [\ell', \mathbf{u}'] : \mathbf{Ax} \geq \mathbf{b}\} \end{aligned}$$

FP for nonconvex MINLPs

Initialization: $\tilde{\mathbf{x}}^0 \in \operatorname{argmin}\{f(\mathbf{x}) : \mathbf{g}(\mathbf{x}) \leq 0\} \in \mathcal{C}$.

1. $k \leftarrow 1$
2. repeat
3. $\hat{\mathbf{x}}^k \in \operatorname{argmin}_{\mathbf{x} \in \mathcal{I}} \Delta'(\mathbf{x}, \tilde{\mathbf{x}}^{k-1})$
4. $\tilde{\mathbf{x}}^k \in \operatorname{argmin}_{\mathbf{x} \in \mathcal{C}} \Delta''(\mathbf{x}, \hat{\mathbf{x}}^k)$
5. $k \leftarrow k + 1$
6. until $\hat{\mathbf{x}}^k$ or $\tilde{\mathbf{x}}^k$ is feasible

Δ' and Δ'' combine **lp distance**, **objective function**, and **second order information** from the problem

Second order information

Consider the (locally!) optimal solution $\tilde{\mathbf{x}}^0$ of the continuous relaxation of the MINLP.

- ▶ If no active constraints, the Hessian of the objective is PSD: $\nabla^2 f(\tilde{\mathbf{x}}^0) \succeq 0$
- ▶ The Hessian of the Lagrangian provides useful info

Using second order information and objective function

Construct PSD matrix P from the Hessian of the Lagrangian by

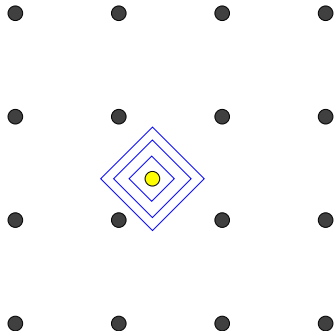
- ▶ Obtaining a projection on the cone of PSD matrices
... (by eliminating negative eigenvalues)

Then use:

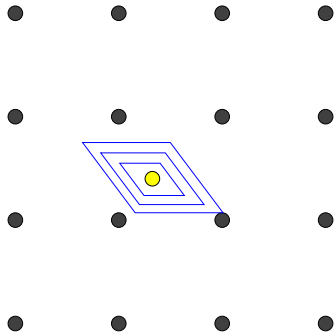
$$\text{MILP: } \Delta'(\mathbf{x}, \bar{\mathbf{x}}) := \alpha' \|\mathbf{x} - \bar{\mathbf{x}}\|_1 + \beta' \|P^{\frac{1}{2}}(\mathbf{x} - \bar{\mathbf{x}})\|_1 + \gamma' \mathbf{c}^\top \mathbf{x}$$

$$\text{NLP: } \Delta''(\mathbf{x}, \bar{\mathbf{x}}) := \alpha'' \|\mathbf{x} - \bar{\mathbf{x}}\|_2 + \beta'' (\mathbf{x} - \bar{\mathbf{x}})^\top P (\mathbf{x} - \bar{\mathbf{x}}) + \gamma'' f(\mathbf{x})$$

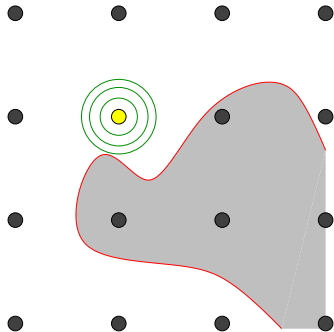
Second-order information: intuition



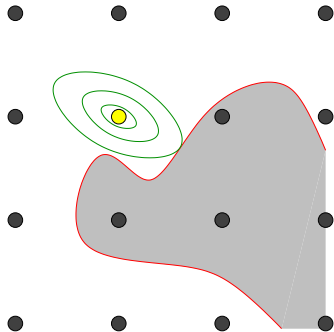
Second-order information: intuition



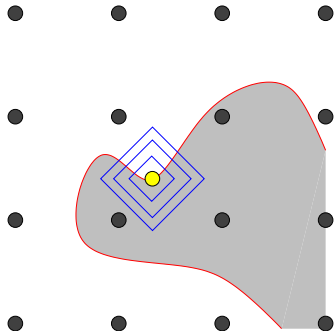
Second-order information: the NLP case



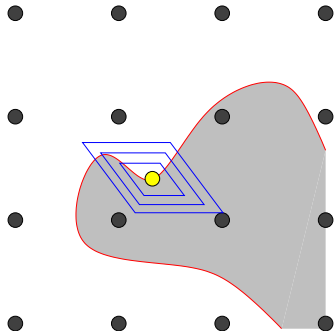
Second-order information: the NLP case



Second-order information: used in the MILP too



Second-order information: used in the MILP too



More features

A **hierarchy** of MILP solvers, from exact&slow to lousy&fast:

1. Solve MILP with node, time limit, emphasis on feasibility
 2. Solve MILP with stricter node, time limit
 3. RENS on MILP
 4. SCIP's own Feasibility Pump
 5. Couenne's rounding-based procedure
 6. Round solution to closest integer
- ▶ If succeeded five times in a row, switch to cheaper method
 - ▶ If current method returns no solution, switch to more expensive one and rerun

Implementation details

Implemented in Couenne, an Open-Source MINLP solver⁶

- ▶ Available in `stable/0.4` (but tested with `trunk`)
- ▶ MILP + heuristics: SCIP⁷
- ▶ NLP solver: Ipopt⁸

Tested on 218 MINLP instances from MINLPLIB⁹

⁶<http://www.coin-or.org/Couenne>

⁷<http://scip.zib.de>

⁸<http://www.coin-or.org/Ipopt>

⁹<http://www.gamsworld.org/minlp/minlplib.htm>

Diving right into the storm¹⁰

Andrea/Antonio/Claudia/Leo's FP found a solution for around 200 out of 243 test instances (compare with 157/218)

Of the stormtroopers' results for the 65 "hard" instances (instances for which only one solver succeeded):

- ▶ 15 times, we find a better solution;
- ▶ 21 times, it is worse

¹⁰D'Ambrosio et al., "A storm of feasibility pumps for nonconvex MINLP." *Math. Prog.* 136:2 (2012), 375-402.

Performance of different versions (single call)

default: ℓ_1 distance for MILP, solved exactly, no cuts

cuts: separate infeasible solutions through conv. cuts

hierarchy: Dynamically chooses MILP methods

hessian: Increase weight for Hessian, decrease for ℓ_2 dist.

objective: Same as **hessian** plus decreasing for objective

simple: Rounding to nearest integer instead of MILP

setting	feasible	better : worse	time (sgm)
default	150	—	14.9
cuts	155	24 : 48	13.6
hierarchy	157	23 : 20	14.0
hessian	154	25 : 16	22.8
objective	138	45 : 30	23.9
simple	97	17 : 78	12.1

MINLP capabilities in the Xpress Optimizer

Heuristics like this can be beneficial for commercial solvers.

In particular for the Xpress Optimizer:

- ▶ MIQCQP: can solve efficiently large problems
- ▶ MISOCP: Fastest solver¹¹, with effective bound reduction and presolver.
- ▶ Both would benefit from a sophisticated heuristic that takes quadratic elements and second-order info into account
- ▶ (MI)NLP: local solver (both first- and second-order NLP); rounding heuristics for integer variables to find good local MINLP solutions.

¹¹Check <http://plato.asu.edu/ftp/socp.html>

Thank You

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